

# Projection heuristics for binary branchings between sum and product

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# SAT solvers and branching trees I

- We consider SAT solvers based on either
  - Look-Ahead (LA)
  - Cube-and-Conquer (C&C)  $\approx$  LA + CDCL (“old and new”).
- Such solvers build a branching (backtracking) tree, with either solved instances at the leaves (LA), or with instances for the conquer-solver (C&C).
- One important heuristic target is to minimise tree-size.

# SAT solvers and branching trees II

- Default branchings are binary (on boolean variables), but can be larger by taking more variables into account (each individual binary branching might be weak, but the whole might be strong).

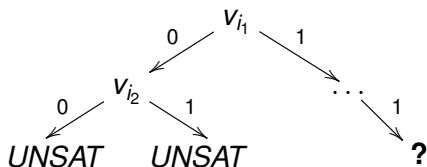
A whole tree  $T$  can be considered as a single branching (leaving out intermediate nodes).

We call this process “flattening”.

To minimise tree size, the best branching should be chosen for every step.

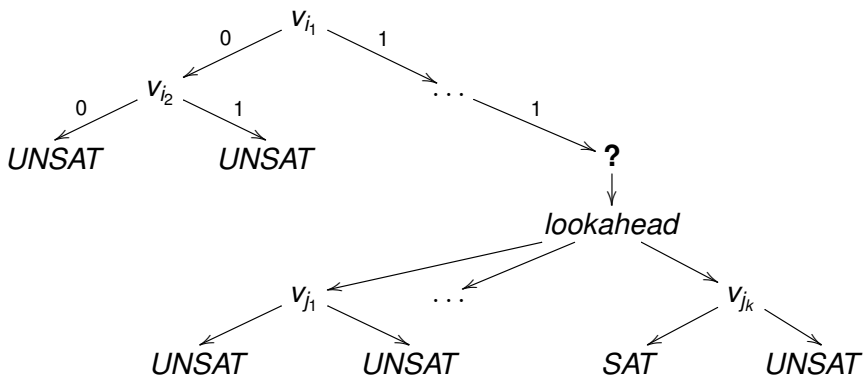
# Branching tree for LA

- Branching variables are chosen via lookahead.
- Non-binary branchings are possible.
- Types of leaves: UNSAT, SAT.



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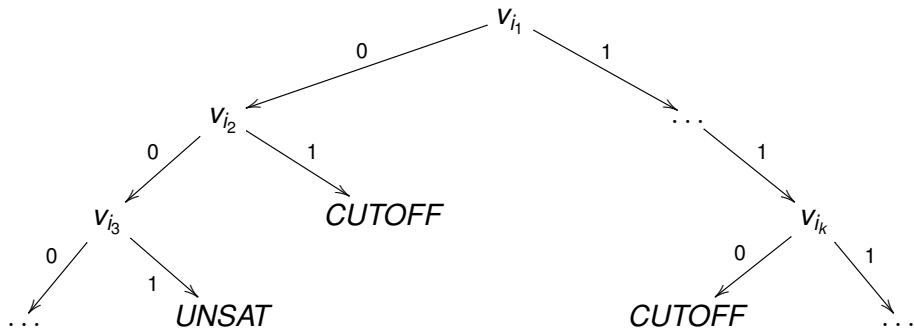


# Branching tree for C&C

Cube cubes are produced by LA solver.

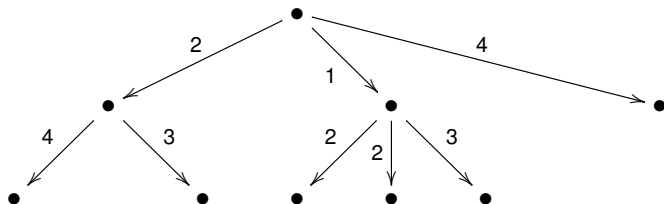
Conquer cubes are solved by specialised solver, by default CDCL.

Now a leaf can be a cutoff-point.



# Trees and distances

The **final** branching tree might look like



The edges (branches) are now labelled with **positive real numbers** (“distances”), showing progress.

- For each branching, a LA solver considers a list of possibilities, based on “looking-ahead and measuring”.
- In general distances can be arbitrary positive real numbers (important for optimisation).

# Branching tuples I

- To every potential branch, a **distance** is considered, a positive real number measuring **progress**.
- Branchings are compared by comparing their **branching tuples** (the tuple of distances).
- The previous tree contains the branching tuples  $(2, 1, 4)$ ,  $(4, 3)$ ,  $(2, 2, 3)$ . Flattening the whole tree yields  $(6, 5, 3, 3, 4, 4)$ .
- A major basic question is:

HOW TO COMPARE BRANCHING TUPLES?



# Branching tuples II

- Choices for distances are:
  - number of variables eliminated
  - number of new clauses (weighted by clause-width).
- In this talk we will consider the distances as given:

The theory works for **ARBITRARY** distances.

# Branching tuples

A **branching tuple** is a tuple  $a = (a_1, \dots, a_k)$  of positive real numbers, with  $k \geq 2$ .

We use  $|a| := k$  for the width.

The set of all branching tuples is

$$\mathcal{BT} := \bigcup_{k=2}^{\infty} (\mathbb{R}_{>0})^k.$$

# Simple comparisons

The task is compare branching tuples,  
finding out which is “better”.

We write  $\mathbf{a} \prec \mathbf{b}$  for “ $a \in \mathcal{BT}$  is strictly better than  $b \in \mathcal{BT}$ ”.

Let's start simple:

- ①  $(1, 2, 3) \prec (1, 2, 2)$  — at least one component better.
- ②  $(3, 2, 1) \prec (1, 2, 2)$  — order doesn't matter.
- ③  $(1, 2) \prec (1, 2, 3)$  — widening always impairs.
- ④  $(2, 1) \prec (1, 2, 3)$  — again, order doesn't matter.
- ⑤  $(2, 2) \prec (1000, 2, 1)$  — combining both methods.

# Trivially better

The order-relation  $\mathbf{a} \preceq \mathbf{b}$

“ $a$  is trivially smaller than  $b$ ”

holds for  $a, b \in \mathcal{BT}$  if the following three conditions are fulfilled:

- ①  $|a| \leq |b|$
- ② there is a permutation  $a'$  of  $a$  with  $\forall i \in \{1, \dots, |a|\} : a'_i \geq b_i$
- ③ either  $|a| < |b|$  or there is  $i \in \{1, \dots, |a|\}$  with  $a'_i > b_i$ .

So all the previous examples for “ $a \prec b$ ” were examples for  $a \preceq b$ .

Reminders:

- “Smaller” here means “better” (smaller tree sizes).
- Smaller branchings have greater distances.
- Additional branches are “bad”.

# Basic axioms for comparing branching tuples

We are seeking to determine a total quasi-order  $\preceq$  on  $\mathcal{BT}$ :

- $a \preceq b$  means “ $a$  is better or equal than  $b$ ”.
- “Total quasi-order” means:
  - $a \preceq a$
  - $a \preceq b \wedge b \preceq c \Rightarrow a \preceq c$
  - $a \preceq b \vee b \preceq a$ .

As usual we define

- $a \simeq b$  if  $a \preceq b$  and  $b \preceq a$  ( $\simeq$  is an equivalence relation on  $\mathcal{BT}$ ),
- $a \prec b$  if  $a \preceq b$  and  $a \not\simeq b$ .

The following two axioms should be indisputable (for all  $a, b \in \mathcal{BT}$ ):

- (S) Symmetry For a permutation  $b$  of  $a$  holds  $a \simeq b$ .
- (T) Trivial comparison If  $a \preceq b$  then  $a \prec b$ .

## A harder case

What about comparing

$$(2, 3) \text{ vs } (1, 4) ?$$

We could invoke here another principle:

“superlinear” growth.

Remember the numbers are changes (indeed reductions) in size (from the same (residual) instance):

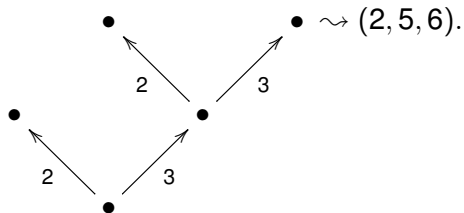
- ① Having “linear” growth means exactly that all tuples with the same sum of entries would be equivalent.
- ② “Superlinear” means that the bad branch here counts more than the good branch, and thus we should have

$$(2, 3) \prec (1, 4).$$

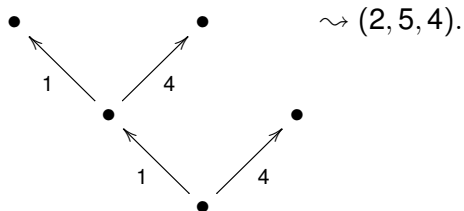
But what about  $(2, 2)$  vs  $(1, 4)$  ?

# Making growth appearing I

Growth can be made explicit by *expansion* and subsequent *flattening*:  
Expand (2, 3) to

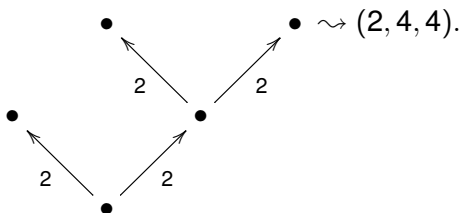


Expand (1, 4) to



# Making growth appearing II

Expand  $(2, 2)$  to



So

- $(2, 3) \rightsquigarrow (2, 5, 6)$
- $(1, 4) \rightsquigarrow (2, 5, 4)$
- $(2, 2) \rightsquigarrow (2, 4, 4)$

Since

$$(2, 5, 6) \preceq (2, 5, 4) \preceq (2, 4, 4)$$

we should have

$$(2, 3) \prec (1, 4) \prec (2, 2).$$

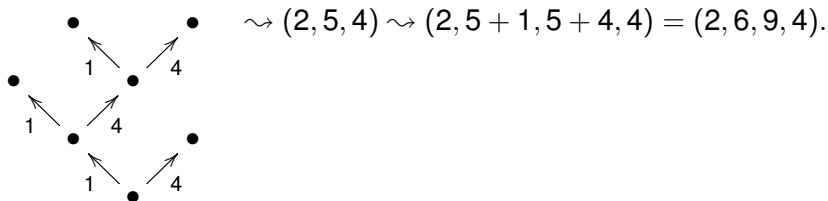


# Expansions

An **expansion** of a branching tuple  $a$  is any branching tuple  $b$  obtained by

- ① considering the tuple  $a$  as a branching constituting the root of a tree, with  $|a|$  many leaves;
- ② replacing leaves iteratively by branching  $a$  (arbitrarily often);
- ③ finally flattening the whole tree (with edges labelled by the numbers of  $a$ ) into one branching tuple  $b$ .

We have already seen three (one-step) expansions. Here is a two-step expansion  $(2, 6, 9, 4)$  of  $(1, 4)$ :



# The Expansion Axiom I

For the order  $\preceq$  on  $\mathcal{BT}$  we are seeking to axiomatically determine, we require now a third axiom (recall the basic two axioms, (S) (Symmetry) and (T) (Trivial comparison)):

(E) Expansion If  $b$  is an expansion of  $a$ , then  $b \simeq a$ .

# The Expansion Axiom II

## Theorem 2.1

For all  $a, b \in \mathcal{BT}$  exactly one of the following four cases holds:

- (i) There are expansions  $a'$  of  $a$  and  $b'$  of  $b$  with  $a' \not\leq b'$ .
- (ii) Same as (i), but with  $b' \leq a'$ .
- (iii) Same as (i), but with  $a'$  being a permutation of  $b'$ .
- (iv) For any expansions  $a', b'$  of  $a, b$  neither  $a' \leq b'$  nor  $b' \leq a'$  holds, nor is  $a'$  a permutation of  $b'$ .

By (S), (T), (E) we get:

Case (i)  $a \prec b$

Case (ii)  $b \prec a$

Case (iii)  $a \simeq b$ .

# The Density Axiom

The order  $\preceq$  is not determined in Case (iv):

- We could just say that  $a \simeq b$  holds for Case (iv).
- But we can indeed conclude this from another intuitive axiom.
- The expansions are somewhat similar to decimal expansions of a number: they get closer and closer to reveal the true “value” of a branching tuple.
- We can indeed capture this by requiring that between  $a \prec b$  there is always some  $c$  with  $a \prec c \prec b$ , where  $c = a - \varepsilon$  for some  $\varepsilon \in \mathbb{R}_{>0}$  (meaning: subtract  $\varepsilon$  from every component of  $a$ ).

(D) Density For  $a \prec b$  there is  $\varepsilon > 0$  such that  
 $a - \varepsilon \in \mathcal{BT}$  and  $a - \varepsilon \prec b$ .

# The Canonical Branching order

Call a total quasi-order  $\preceq$  on  $\mathcal{BT}$  fulfilling (S), (T), (E), (D) a  
**canonical branching order.**

## Theorem 2.2

*There is exactly one canonical branching order.*

We now turn to concretely determine the canonical branching order.

(This also will show that comparisons  $a \prec b$ ,  $a \preceq b$  and  $a \simeq b$  are decidable in polynomial time for  $a, b$  made from algebraic numbers.)

# Measuring branching tuples

We define  $\tau : \mathcal{BT} \rightarrow \mathbb{R}_{>1}$  by

- $\tau(a, b)$  is the unique  $x > 1$  with  $x^{-a} + x^{-b} = 1$ .
- $\tau(a, b, c)$  is the unique  $x > 1$  with  $x^{-a} + x^{-b} + x^{-c} = 1$ .
- And so on.

This generalises the so-called “characteristic polynomial” of difference and differential equations.

The tau-function evaluates branching tuples (the smaller the tau-value the better the branching tuple), and the derived ordering of branching tuples is the canonical branching order:

## Theorem 2.3

*For  $a, b \in \mathcal{BT}$  holds  $a \preceq b \Leftrightarrow \tau(a) \leq \tau(b)$ .*

# Variants of the tau-function

For numeric purposes **log-tau**  $l\tau : \mathcal{BT} \rightarrow \mathbb{R}_{>0}$  is more appropriate:

$$l\tau(\mathbf{a}) := \ln(\tau(\mathbf{a})).$$

Obviously  $\tau(\mathbf{a}) \leq \tau(\mathbf{b}) \Leftrightarrow l\tau(\mathbf{a}) \leq l\tau(\mathbf{b})$ .

In a sense log-tau computes a sort of “mean value” of a branching tuple — we get indeed a proper form of a mean value, called **mean-tau**  $\mathfrak{T} : \mathcal{BT} \rightarrow \mathbb{R}_{>0}$  by taking the reciprocal value and scaling:

$$\mathfrak{T}(\mathbf{a}) := \frac{\ln(|\mathbf{a}|)}{l\tau(\mathbf{a})}.$$

# Binary tau

Currently for SAT most important is binary log-tau:

$$l_{\tau}(x, y) := l_{\tau}((x, y)).$$

We get a very good handle on  $l_{\tau}(x, y)$  by reducing it to **w-tau**

$w_{\tau} : \mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0}$ , a function with just one argument:

$$w_{\tau}(x) := l_{\tau}\left(1, \frac{1}{x}\right)$$

$$l_{\tau}(x, y) = \frac{1}{x} w_{\tau}\left(\frac{x}{y}\right).$$

W-tau is asymptotically equal to the Lambert-W function, which in turn is asymptotically equal to the logarithm:

$$|w_{\tau}(x) - W(x)| = o(1)$$

$$|W(x) - \ln(x)| = O(1)$$

Warning: These approximations are bad for (relevant) “small”  $x$ .



# Alternatives to binary tau?

Given a binary branching tuple  $(x, y) \in \mathcal{BT}_2 := (\mathbb{R}_{>0})^2$ , we determine its “value” by  $\tau(x, y)$  (or  $|\tau(x, y)|$ ):

The proof that this is the only way  
hinges on having arbitrarily large trees  
containing (only)  $(x, y)$ .

But this is not applicable to inputs (or residual instances) of finite size — can (should?) we take this into account?!?

For the remainder our projections (maps from  $\mathcal{BT}_2$  to  $\mathbb{R}_{>0}$ ) are to be maximised (the larger the better).

Historically

- ① first the “projection”  $(x, y) \mapsto x + y$  was used (sum rule)
- ② which was soon replaced by  $(x, y) \mapsto x \cdot y$  (product rule).

# An axiomatic framework for binary projections

Starting from the (generalised) mean  $\mathfrak{T} : \mathcal{BT} \rightarrow \mathbb{R}_{>0}$ , we consider the following seven axioms for binary projections  $m : \mathcal{BT}_2 \rightarrow \mathbb{R}_{>0}$ , now using “the larger the better” (for all  $x, y, x', y' \in \mathbb{R}_{>0}$ ):

- (i)  $m(x, y) = m(y, x)$  (symmetry)
- (ii)  $m$  strictly increasing in each component
- (iii)  $\min(x, y) \leq m(x, y) \leq \max(x, y)$  (consistency)
- (iv)  $\lambda > 0 \implies m(\lambda \cdot x, \lambda \cdot y) = \lambda \cdot m(x, y)$  (homogeneity – scale invariance)
- (v)  $0 \leq \lambda \leq 1 \implies m(\lambda \cdot x + (1 - \lambda) \cdot x', \lambda \cdot y + (1 - \lambda) \cdot y') \geq \lambda \cdot m(x, y) + (1 - \lambda) \cdot m(x', y')$  (concavity)
- (vi)  $\lim_{x \rightarrow \infty} m(x, y) = \infty$  ( $\infty$ -dominated)
- (vii)  $\lim_{x \rightarrow 0} m(x, y) = 0$  (0-dominated).

$\mathfrak{T}_2$  fulfils these seven axioms.

# Power means

The first four axioms are fulfilled by the power means  $m_p : \mathcal{BT}_2 \rightarrow \mathbb{R}_{>0}$ , defined for  $-\infty \leq p \leq +\infty$  as follows:

- ①  $m_{-\infty}(x, y) = \min(x)$  (the “most pessimistic choice”)
- ②  $m_{+\infty}(x, y) = \max(x)$  (the “most optimistic choice”)
- ③  $m_0(x, y) = \sqrt{x \cdot y}$  (the geometric mean)
- ④ otherwise  $m_p(x, y) = (\frac{1}{2}(x^p + y^p))^{1/p}$ .

$m_1$  is the arithmetic mean,  $m_{-1}$  is the harmonic mean.

The choice of  $m_1$  corresponds to the “sum-rule”,  
the choice of  $m_0$  to the “product rule”.

- $m_p$  is concave iff  $p \leq 1$ .
- $m_p$  is  $\infty$ -dominated iff  $p \geq 0$ .
- $m_p$  is 0-dominated iff  $p \leq 0$ .

So  $m_0$  is the only power means fulfilling all seven axioms.

# Reducing binary means to their kernels

For comparing means  $m : \mathcal{BT}_2 \rightarrow \mathbb{R}_{>0}$ , thanks to symmetry and homogeneity we can restrict attention to their “kernels”

$$\bar{m} : \mathbb{R}_{\geq 1} \rightarrow \mathbb{R}_{\geq 1}$$

defined by

$$\bar{m}(x) := m(1, x).$$

$\bar{m}(x)$  says how much imbalanced branching tuples are penalised — the large  $\bar{m}(x)$  the less penalisation.

For  $0 \leq p \leq 1$ :

- ①  $\bar{m}_1(x) = \frac{1}{2} + \frac{x}{2}$  penalises the least.
- ②  $\bar{m}_0(x) = \sqrt{x}$  penalises the most.

$\bar{\mathfrak{T}}(x) \sim \frac{x}{\log_2(x)}$  penalises less than  $m_0$ ,  
and more than  $m_p$  for  $p \leq 0.307$ .

# Future research

- I Develop a dynamic binary projection, which takes the changing scales into account: more penalisation towards the root, less towards the leaves.
- II Generalise the results for binary-tau to non-binary tau.
- III Make use of the numeric values of the tau-function (not just using it for comparison) — the tau-value yields a global evaluation of the current state of the search.

# End

(references on the remaining slides).

For my papers see

<http://cs.swan.ac.uk/~csoliver/papers.html>.

# Bibliography I

- [1] Oliver Kullmann. Fundamentals of branching heuristics. In Armin Biere, Marijn J.H. Heule, Hans van Maaren, and Toby Walsh, editors, *Handbook of Satisfiability*, volume 185 of *Frontiers in Artificial Intelligence and Applications*, chapter 7, pages 205–244. IOS Press, February 2009. ISBN 978-1-58603-929-5. doi:[10.3233/978-1-58603-929-5-205](https://doi.org/10.3233/978-1-58603-929-5-205).