

CSP: Constraint Programming

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Overview

Constraint Programming

- Modelling
- Search space size
- Primal / Dual models
- Global constraints
- Solving
- Guidelines
- CP Styles

Constraint Programming

CP:

- provides a platform for solving CSPs
- proven useful in many real applications

Platform:

- set of common structures to reuse
- best known algorithms for propagation & solving

Two stages:

- modelling
- solving

CP: Modelling

Modelling decisions: select among alternatives

- the choice of the variables
 - the choice of the domains
 - how we state the constraints
- } *search space size*
← *space reduction*

Example: Map Colouring

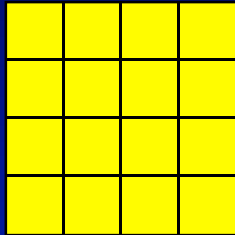
- variables: are regions or colours?

Any CSP can be modelled in different ways

- Efficiency of algorithms can vary dramatically
- No strong results are known
- Formulating an effective model is not easy, requires considerable skills in modelling

N-queens: Model 1

Variables: n^2 , one per cell, matrix B $n \times n$



Domains: $\{0,1\}$, $B[a,b]=0$, no queen
 $B[a,b]=1$, queen

Constraints: If $B[a,b] = 1$ then

same row $B[_,b]=0$ \square

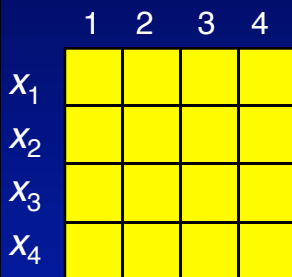
same column $B[a,_]=0$ \square

same diagonal $B[a+\square,b+\square]=0$, $B[a-\square,b-\square]=0$ \square

same diagonal $B[a-\square,b+\square]=0$, $B[a+\square,b-\square]=0$ \square

N-queens: Model 2

Variables: n , one per row



Domains: $\{0,1,\dots,n-1\}$, queen column

Constraints:

different columns $x_i \neq x_j$ \square

different diagonals $|x_i - x_j| \neq |i - j|$

Different row constraint is included in the formulation!!

N-queens: Model 3

	1	2	3	4
x_1				
x_2				
x_3				
x_4				

Variables: n , one per row

Domains: $\{0, 1, \dots, n-1\}$, queen column

Constraints:

different columns all-different(x_1, x_2, \dots, x_n) \square

different diagonals $|x_i - x_j| \neq |i - j|$

Different row constraint is included in the formulation!!

N-queens Models

	Model 1	Model 2	Model 3
Search space size	2^{n^2}	n^n	n^n
$d \#vars$	4 65,536	256	256
	10 1.27 E30	1.00 E10	1.00 E10
	20 ERROR!!	1.05 E26	1.05 E26
Constraints number	n rows n columns 2(n-1) diagonals	n columns 2(n-1) diagonals	1 all-diff 2(n-1) diagonals
pruning		Equal model 1	More than model 2

Constraint Formulations

Binary (arity ≤ 2) :

- conceptually simple, easy to implement
- may generate weak formulations

Non-binary (arity > 2) :

- more complex constraints
- GAC: stronger (filter more) than AC on equivalent binary decomposition

Equivalence: any non-binary CSP can be reformulated as a binary one

Primal / Dual Formulations

Primal CSP: (X, D, C)

$X = \{x_1, x_2, \dots, x_n\}$, $D = \{d_1, d_2, \dots, d_n\}$, $C = \{c_1, c_2, \dots, c_r\}$

Dual CSP: (X', D', C')

$X' = \{x'_1, x'_2, \dots, x'_r\}$, $D' = \{d'_1, d'_2, \dots, d'_r\}$, $C' = \{c'_{ij}\}$

*one variable per
primal constraint*

$d'_i = rel(c_i)$

*values=permitted
primal tuples*

$var(c'_{ij}) = \{x'_i, x'_j\}$

$\{c'_{ij} \in C' \mid$

$var(c_i) \cap var(c_j) \neq \emptyset$

$rel(c'_{ij})$ =same values
for shared
primal vars

Always binary!!

Example: Crossword puzzles

1	2	3	4	5
6	7	8		9
10	11	12	13	14
15		16	17	18
19	20	21	22	23

a
aardvark
aback
abacus
abaft
abalone
abandon
...

monarch
monarchy
monarda
...
zymurgy
zyrian
zythum

Primal model (Non-binary)

1	2	3	4	5
6	7	8		9
10	11	12	13	14
15		16	17	18
19	20	21	2	2
			2	3

variables: cells

domains: 'a', ..., 'z'

constraints: contiguous
letters must form words in
dictionary

Dual model (binary)

1	2	3	4	5
6	7	8		9
10	11	12	13	14
15		16	17	18
19	20	21	2	2
			2	3

variables: words across and down

domains: words from dictionary

constraints: intersecting words must agree on common letter

Hidden Variable Formulation

Primal CSP: (X, D, C)

$X = \{x_1, \dots, x_n\}$, $D = \{d_1, \dots, d_n\}$, $C = B \sqcup \{c_a, \dots, c_q\}$

Hidden formulation: (X', D', C')

$X' = X \sqcup \{x_a, \dots, x_q\}$, $D' = D \sqcup \{d_a, \dots, d_q\}$, $C' = B \sqcup \{c_{ip}\}$

a new variable per non-binary constraint

$d_p = rel(c_p)$
values=permitted
primal tuples

$var(c_{ip}) = \{x_i, x_p\}$
 $\sqcup c_{ip} \sqcup C'$
 $x_i \sqcup var(c_p) \sqcup rel(c_{ip}) =$ same values for x_j

hidden variables

Global Constraints

Real-life constraints: often complex, non-binary

c is global iff:

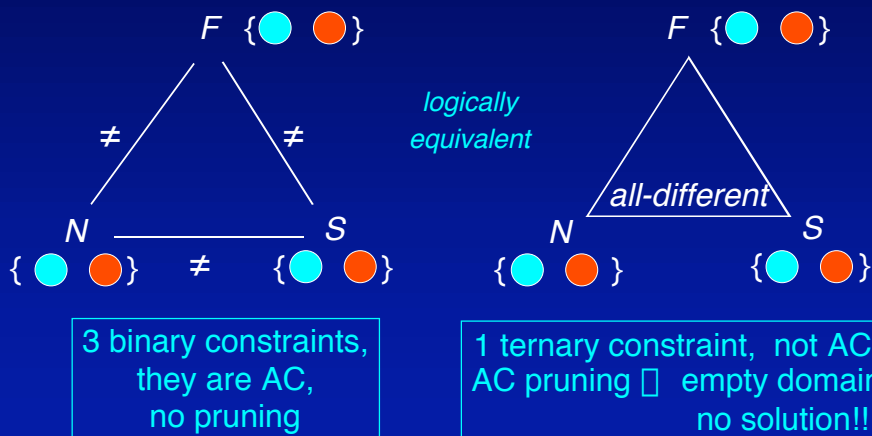
- $\text{arity}(c) > 2$
- c is logically equivalent to $\{c_1, c_2, \dots, c_k\}$ binary
- $\text{AC}(c)$ *prunes more* than $\text{AC}(c_1, c_2, \dots, c_k)$

Propagation:

- specialized algorithms
- exploit constraint semantics *decrease AC complexity*

Example: *all-different*

Var: F, N, S ; Val: { ● ● }; Ctrs: $N \neq S \neq F \neq N$



Example: *all-different*

Enforcing arc-consistency:

- n variables, d values
- $n(n-1)/2$ binary constraints : $O(n^2 d^2)$
- 1 n -ary constraint:
 - general purpose algorithm $O(d^n)$
 - specialized algorithm $O(n^2 d^2)$

CP: Solving

Solving decisions: select among alternatives

- search algorithm
 - local consistency: level / how often
 - heuristics: variable / value
- } *interleaved*

Example: Map Colouring

- static or dynamic variable ordering ?

Efficient solving:

- reasonable initial size of the search space
- drastic *reductions* of space during search

CP Solving: Some Guidelines

Easy/hard problems:

- hybrid search
- dynamic variable ordering: min domain / degree
- easy: FC / hard: MAC

One solution/All solutions:

- one solution: hybrid search
- all solutions: hybrid search or complete inference

For specific problems (scheduling, routing...) check:

- formulation, global constraints
- heuristics, experiences

CP: Declarative Programming

Declarative Programming: you declare

- Variables
- Domains
- Constraints

and ask the SOLVER to find a solution!!

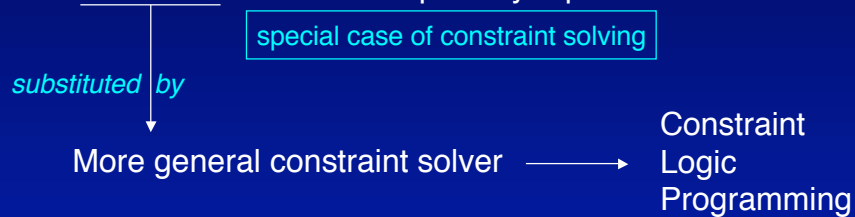
SOLVER offers:

- Implementation for variables / domains / constraints
- Hybrid algorithm: backtracking + incomplete inference
- Global constraints + optimized AC propagation
- Empty domain detection
- Embedded heuristics

Constraint Logic Programming

Logic Programming:

- Depth-first search
- Unification: *substitute* equals by equals clauses/database



Existing solvers:

- Chip, Eclipse, Mozart, Sictus Prolog (and many others)

Constraint Programming Libraries

Library to be included in your program:

- Imperative programming

Provides:

- Special objects:
 - Variables / Domains / Constraints (global)
- Special functions to find:
 - One solution / the next solution

Existing Solvers:

- Ilog Solver, Choco