

Towards Industrial-like Random SAT Instances

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- SAT is a central problem in computer science and AI
- The problem is NP-complete
- State-of-the-art solvers (heuristics, backjumping, learning, restarts, . . .) are of practical use with real-world SAT instances
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What is a “real-world” SAT instance?



SAT Competitions

- SAT competitions evaluate ideas, techniques and solvers
- Competitions use **benchmarks**:
 - Randomly generated
 - ⇒ Unlimited in number
 - ⇒ Families of instances: one for every number of vars
 - ⇒ Generated on demand: fair in competitions
 - ⇒ Parameterized degree of difficulty
 - Industrial
 - ⇒ Limited in number
 - ⇒ Specially valuable
 - Crafted

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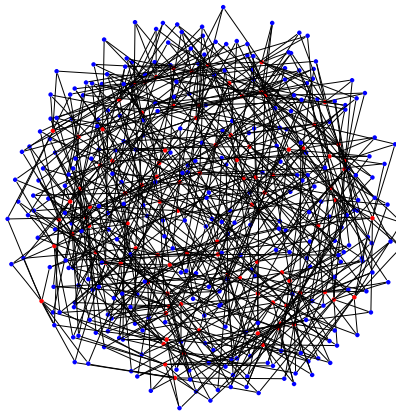
**Create generators of random instances
with properties similar to industrial ones to test solvers**

Stated as 10th challenge by [Kautz&Sellman](#) in “Ten Challenges in Propositional Reasoning and Search”:

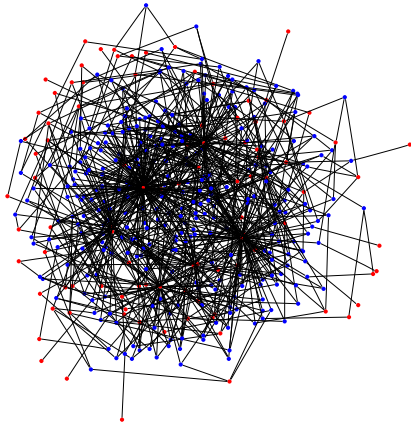
Develop a generator for problem instances that have computational properties that are more similar to real-world instances[...] While hundreds of specific [industrial] problems are available, it would be useful to be able to randomly generate similar problems by the thousands for testing purposes

Also [Rina Dechter](#) in her book proposes the same objective

Random 3-CNF



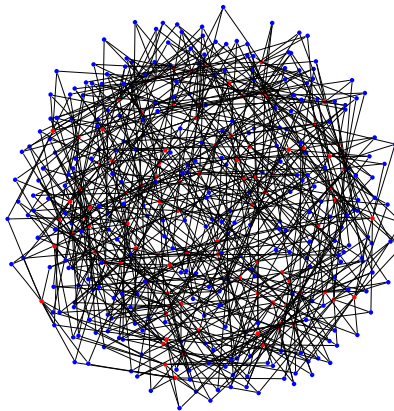
Real-World Instance



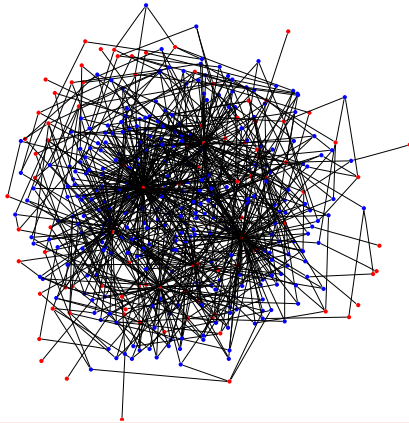
Bi-partite graph: Nodes: are variables **v** and clauses **c**
Edges: **v**—**c** if clause **c** contains variable **v**

Arity of nodes: number of variable occurrences $\approx 4.25 * 3 = 12.75$
and clause size ≈ 3

Random 3-CNF



Real-World Instance



Real-world instances contain hubs, are scale-free graphs !!!

⇒ See our paper at CP'09

Main Idea

Choose variables (and clauses) randomly following a **non-uniform** probability distribution

$$P[X = i] = \phi(i; n)$$



The distribution depends on the number of variables

Example: Take $\phi(i; n) = \frac{1-b}{1-b^n} b^i$ with $0 < b \leq 1$

Construct clauses of size 3 randomly selecting 3 distinct variables following this probability distribution

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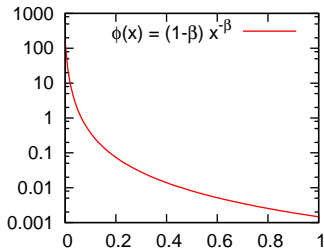
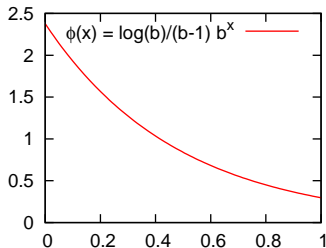
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Problem: the phase-transition point depends on n !!!

Families of Probability Distributions



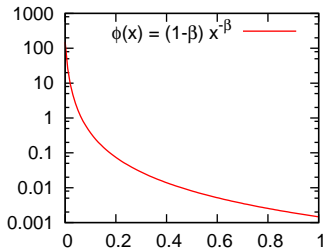
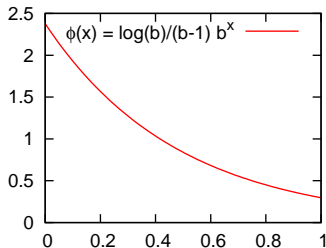
Given a continuous prob. distribution function in $[0, 1]$

$$\phi^{geo}(x; b) = \frac{\ln(b)}{b-1} b^x \quad \phi^{pow}(x; \beta) = (1-\beta) x^{-\beta}$$

Define $P(X = i; n) \propto \phi(i/n)$ taking n equidistant points:

$$P(i; b, n) = \frac{1 - b^{1/n}}{1 - b} b^{i/n} \quad P(i; \beta, n) = \frac{i^{-\beta}}{\sum_{j=1}^n j^{-\beta}}$$

Families of Probability Distributions



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$$\phi^{geo}(x; b) = \frac{\ln(b)}{b-1} b^x \quad \phi^{pow}(x; \beta, \epsilon) = \frac{1-\beta}{(1+\epsilon)^{1-\beta} - \epsilon^{1-\beta}} (x+\epsilon)^{-\beta}$$

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$$P(i; b, n) = \frac{1 - b^{1/n}}{1 - b} b^{i/n} \quad P(i; \beta, \epsilon, n) = \frac{(i + \epsilon \cdot n)^{-\beta}}{\sum_{j=1}^n (j + \epsilon \cdot n)^{-\beta}}$$

(Uniform) Generator

Input: n, m, k, b

Output: a k -SAT instance with n variables and m clauses

$F = \emptyset$

for $i = 1$ **to** m **do**

repeat

$C_i = \square$

for $j = 1$ **to** k **do** $\text{rand}([0\ 1]) \rightarrow$

$p = \text{rand}([0\ 1])$

$v = 0$

while $p > \text{Pr}(v; b, n)$ **do**

$v = v + 1$

$p = p - P(v; b, n)$

$C_i = C_i \vee (-1)^{\text{rand}(\{0,1\})} \cdot v$

0] $P(0; b, n)$

] $P(1; b, n)$

] $P(2; b, n)$

...

1] $P(n-1; b, n)$

until C_i is not a tautology or simplifiable

$F = F \cup \{C_i\}$

Regular Generator

Input: n, m, k, b

Output: a k -SAT instance with n variables and m clauses

$bag = \emptyset$

for $v = 1$ **to** n **do**

$bag = bag \cup \left\{ \left\lfloor P(v; B, n) \frac{k m}{2} \right\rfloor \text{ copies of } v \right\}$

$bag = bag \cup \left\{ \left\lfloor P(v; B, n) \frac{k m}{2} \right\rfloor \text{ copies of } \bar{v} \right\}$

endfor

$S =$ subset of $k m - |bag|$ literals from $\{1, \dots, n, \bar{1}, \dots, \bar{n}\}$

maximizing $Pr(v; b, n) \frac{k m}{2} - \lfloor Pr(v; b, n) \frac{k m}{2} \rfloor$

$bag = bag \cup S$

repeat

$F = \emptyset$

for $i = 1$ **to** m **do**

$C_i =$ random multiset of k literals from bag

$bag = bag \setminus C_i$

$F = F \cup \{C_i\}$

until F does not contain tautologies or simplifiable clauses

Generator of Clauses of Variable Size

```
Input:     $n, m, k, \beta_v, \beta_c$   
Output:  a SAT instance with  $n$  variables,  $m$  clauses  
for  $i = 1$  to  $m$  do  
     $C_i := \square$ ;  
for  $i = 1$  to  $k * m$  do  
    repeat  
         $p := rand()$ ;  $v := 1$ ;  
        while  $p > P(v; \beta_v, n)$  do  
             $p := p - P(v; \beta_v, n)$ ;  $v := v + 1$ ;  
        endwhile  
         $p := rand()$ ;  $c := 1$ ;  
        while  $p > P(c; \beta_c, m)$  do  
             $p := p - P(c; \beta_c, m)$ ;  $c := c + 1$ ;  
        endwhile  
        while  $v \in C_c$   
             $C_c := C_c \vee (-1)^{rand(2)} \cdot v$ ;  
    endfor
```

What Distribution Fits Better?

- Analyzed 100 instances of the SAT Race 2008
- $n = 25.693.792$ variables
- $\sum_{i=1}^n N(i) = 349.760.681$ occurrences
- $E[N(i)] = \sum_{i=1}^n N(i)/n = 13.6$ average number of occurrences

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60% have 6 or less occurrences

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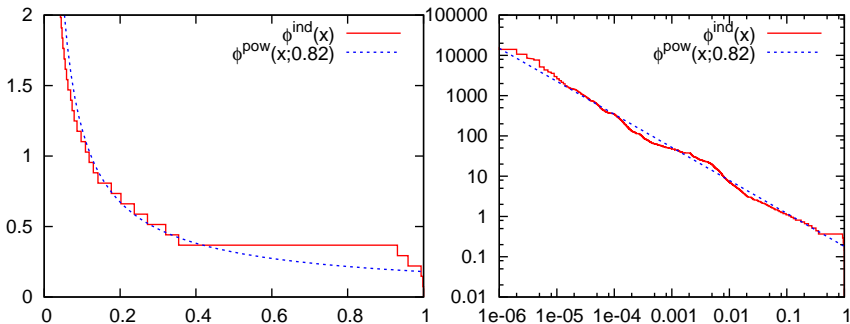
- 90% of variables have less than this number of occurrences
60% have 6 or less occurrences
- Let $N(i)$ = number of occurrences of the i th most frequent variable ($N(i) \geq N(i + 1)$)
- Estimate

$$\phi^{ind}(i/n) = \frac{n}{\sum_{j=1}^n N(j)} N(i)$$

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Probabilities of Variables/Occurrences

Do not confuse:

$$P(X = i) \sim \phi(i/n)$$

Probability that **variable** i is chosen to be included in a clause

$$P(O = k)$$

Probability that a randomly chosen variable has k **occurrences** in the generated formula

Theorem

In the powerlaw model, with $\phi^{\text{pow}}(x; \beta) = (1 - \beta)x^{-\beta}$, when n tends to ∞ , the probability that a variable has k occurrences follows a powerlaw distribution $P(k) \sim k^{-\alpha}$, where $\alpha = 1/\beta + 1$.

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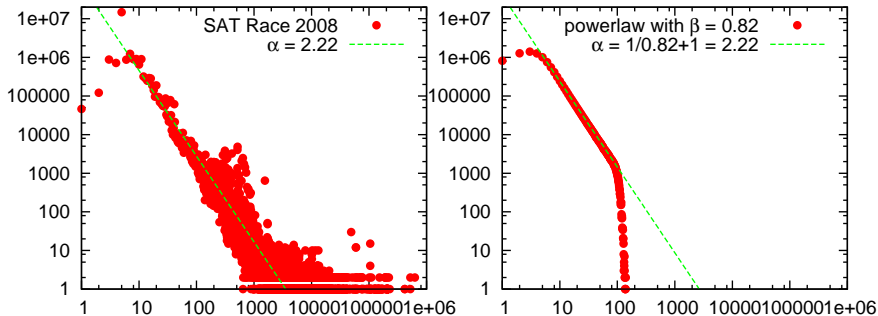
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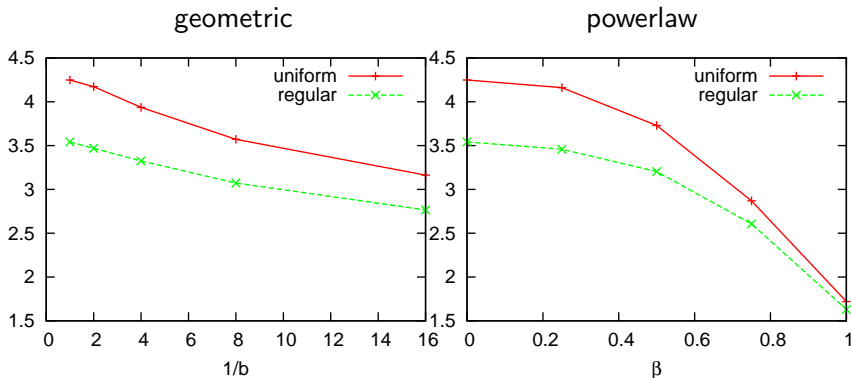
Prob. Dist. of Num. of Occurrences



- SAT Race'08 var. occurrences follow a powerlaw distribution with $\alpha = 2.22$
- Random instances generated with $\phi^{pow}(x; \beta)$, where $\beta = 0.82$, too

$$\alpha = 2.22 = \frac{1}{0.82} + 1 = \frac{1}{\beta} + 1$$

Phase Transition Point



Remember:

geometric model
with $b = 1$

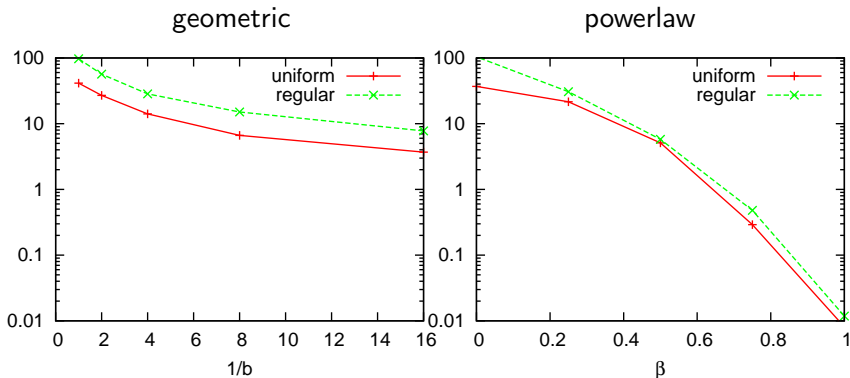
=

powerlaw model
with $\beta = 0$

=

classical random
3-CNF model

How Industrial Instances Look Like?



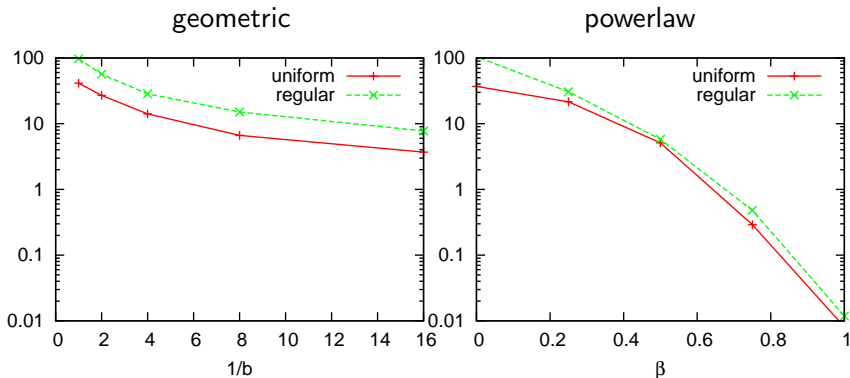
Graphics show:

$\frac{\text{minisat CPU time}}{\text{kcnf CPU time}}$

Specialized in industrial inst.

Specialized in random inst.

How Industrial Instances Look Like?



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$$\frac{\text{minisat CPU time}}{\text{kcnf CPU time}}$$

Minisat beat **kcnf** in the **powerlaw** model,
but not in the **geometric**

Conclusions

- We have capture some properties of some industrial instances like **powerlaw distribution** of the number of **occurrences** and of the **clause size**
- **Behavior of solvers** show that we are on the right path to understand the nature of real-world instances
- In **CP'09**, we'll show a more complete study of families of industrial instances and the **effect of solvers** (learning, instantiation) on the structure of formulas
- **Future work**: Study other **structural** properties of industrial instances (symmetries, self-similarity,...)